

CS70: Jean Walrand: Lecture 31.

Nonlinear Regression

1. Review: joint distribution, LLSE
2. Quadratic Regression
3. Definition of Conditional expectation
4. Properties of CE
5. Applications: Diluting, Mixing, Rumors
6. CE = MMSE

Quadratic Regression

Let X, Y be two random variables defined on the same probability space.

Definition: The quadratic regression of Y over X is the random variable

$$Q[Y|X] = a + bX + cX^2$$

where a, b, c are chosen to minimize $E[(Y - a - bX - cX^2)^2]$.

Derivation: We set to zero the derivatives w.r.t. a, b, c . We get

$$\begin{aligned} 0 &= E[Y - a - bX - cX^2] \\ 0 &= E[(Y - a - bX - cX^2)X] \\ 0 &= E[(Y - a - bX - cX^2)X^2] \end{aligned}$$

We solve these three equations in the three unknowns (a, b, c) .

Note: These equations imply that $E[(Y - Q[Y|X])h(X)] = 0$ for any $h(X) = d + eX + fX^2$. That is, the estimation error is orthogonal to all the quadratic functions of X . Hence, $Q[Y|X]$ is the projection of Y onto the space of quadratic functions of X .

Review

Definitions Let X and Y be RVs on Ω .

- ▶ **Joint Distribution:** $Pr[X = x, Y = y]$
- ▶ **Marginal Distribution:** $Pr[X = x] = \sum_y Pr[X = x, Y = y]$
- ▶ **Conditional Distribution:** $Pr[Y = y|X = x] = \frac{Pr[X=x, Y=y]}{Pr[X=x]}$
- ▶ **LLSE:** $L[Y|X] = a + bX$ where a, b minimize $E[(Y - a - bX)^2]$.

We saw that

$$L[Y|X] = E[Y] + \frac{\text{cov}(X, Y)}{\text{var}[X]}(X - E[X]).$$

Recall the non-Bayesian and Bayesian viewpoints.

Conditional Expectation

Definition Let X and Y be RVs on Ω . The **conditional expectation** of Y given X is defined as

$$E[Y|X] = g(X)$$

where

$$g(x) := E[Y|X = x] := \sum_y y Pr[Y = y|X = x].$$

Fact

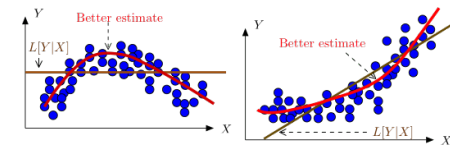
$$E[Y|X = x] = \sum_{\omega} Y(\omega) Pr[\omega|X = x].$$

Proof: $E[Y|X = x] = E[Y|A]$ with $A = \{\omega : X(\omega) = x\}$. □

Nonlinear Regression: Motivation

There are many situations where a good guess about Y given X is not linear.

E.g., (diameter of object, weight), (school years, income), (PSA level, cancer risk).



Our goal: explore estimates $\hat{Y} = g(X)$ for nonlinear functions $g(\cdot)$.

Deja vu, all over again?

Have we seen this before? Yes.

Is anything new? Yes.

The idea of defining $g(x) = E[Y|X = x]$ and then $E[Y|X] = g(X)$.

Big deal? Quite! Simple but most convenient.

Recall that $L[Y|X] = a + bX$ is a function of X .

This is similar: $E[Y|X] = g(X)$ for some function $g(\cdot)$.

In general, $g(X)$ is not linear, i.e., not $a + bX$. It could be that $g(X) = a + bX + cX^2$. Or that $g(X) = 2\sin(4X) + \exp\{-3X\}$. Or something else.

Properties of CE

$$E[Y|X = x] = \sum_y yPr[Y = y|X = x]$$

Theorem

- (a) X, Y independent $\Rightarrow E[Y|X] = E[Y]$;
- (b) $E[aY + bZ|X] = aE[Y|X] + bE[Z|X]$;
- (c) $E[Yh(X)|X] = h(X)E[Y|X], \forall h(\cdot)$;
- (d) $E[h(X)E[Y|X]] = E[h(X)Y], \forall h(\cdot)$;
- (e) $E[E[Y|X]] = E[Y]$.

Proof:

- (a),(b) Obvious
- (c) $E[Yh(X)|X = x] = \sum_{\omega} Y(\omega)h(X(\omega))Pr[\omega|X = x]$
 $= \sum_{\omega} Y(\omega)h(x)Pr[\omega|X = x] = h(x)E[Y|X = x]$

Properties of CE

Theorem

- (a) X, Y independent $\Rightarrow E[Y|X] = E[Y]$;
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- (e) $E[E[Y|X]] = E[Y]$.

Note that (d) says that

$$E[(Y - E[Y|X])h(X)] = 0.$$

We say that the estimation error $Y - E[Y|X]$ is orthogonal to every function $h(X)$ of X .

We call this the **projection property**. More about this later.

Properties of CE

$$E[Y|X = x] = \sum_y yPr[Y = y|X = x]$$

Theorem

- (a) X, Y independent $\Rightarrow E[Y|X] = E[Y]$;
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- (e) $E[E[Y|X]] = E[Y]$.

Proof: (continued)

$$\begin{aligned} \text{(d) } E[h(X)E[Y|X]] &= \sum_x h(x)E[Y|X = x]Pr[X = x] \\ &= \sum_x h(x) \sum_y yPr[Y = y|X = x]Pr[X = x] \\ &= \sum_x h(x) \sum_y yPr[X = x, Y = y] \\ &= \sum_{x,y} h(x)yPr[X = x, Y = y] = E[h(X)Y]. \end{aligned}$$

Application: Calculating $E[Y|X]$

Let X, Y, Z be i.i.d. with mean 0 and variance 1. We want to calculate

$$E[2 + 5X + 7XY + 11X^2 + 13X^3Z^2|X].$$

We find

$$\begin{aligned} E[2 + 5X + 7XY + 11X^2 + 13X^3Z^2|X] &= 2 + 5X + 7XE[Y|X] + 11X^2 + 13X^3E[Z^2|X] \\ &= 2 + 5X + 7XE[Y] + 11X^2 + 13X^3E[Z^2] \\ &= 2 + 5X + 11X^2 + 13X^3(\text{var}[Z] + E[Z]^2) \\ &= 2 + 5X + 11X^2 + 13X^3. \end{aligned}$$

Properties of CE

$$E[Y|X = x] = \sum_y yPr[Y = y|X = x]$$

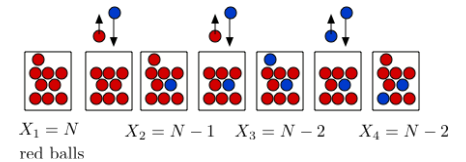
Theorem

- (a) X, Y independent $\Rightarrow E[Y|X] = E[Y]$;
- (b) $E[aY + bZ|X] = aE[Y|X] + bE[Z|X]$;
- (c) $E[Yh(X)|X] = h(X)E[Y|X], \forall h(\cdot)$;
- (d) $E[h(X)E[Y|X]] = E[h(X)Y], \forall h(\cdot)$;
- (e) $E[E[Y|X]] = E[Y]$.

Proof: (continued)

- (e) Let $h(X) = 1$ in (d). □

Application: Diluting



At each step, pick a ball from a well-mixed urn. Replace it with a blue ball. Let X_n be the number of red balls in the urn at step n . What is $E[X_n]$?

Given $X_n = m$, $X_{n+1} = m - 1$ w.p. m/N (if you pick a red ball) and $X_{n+1} = m$ otherwise. Hence,

$$E[X_{n+1}|X_n = m] = m - (m/N) = m(N-1)/N = X_n \rho,$$

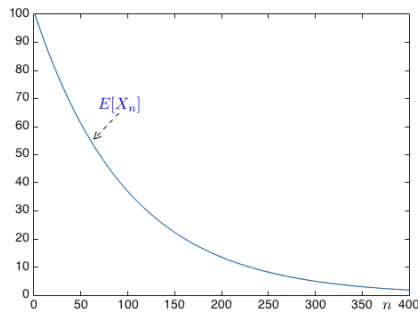
with $\rho := (N-1)/N$. Consequently,

$$E[X_{n+1}] = E[E[X_{n+1}|X_n]] = \rho E[X_n], n \geq 1.$$

$$\Rightarrow E[X_n] = \rho^{n-1} E[X_1] = N \left(\frac{N-1}{N}\right)^{n-1}, n \geq 1.$$

Diluting

Here is a plot:



Mixing

We saw that $E[X_{n+1}|X_n] = 1 + \rho X_n$, $\rho := (1 - 2/N)$. Hence,

$$\begin{aligned} E[X_{n+1}] &= 1 + \rho E[X_n] \\ E[X_2] &= 1 + \rho N; E[X_3] = 1 + \rho(1 + \rho N) = 1 + \rho + \rho^2 N \\ E[X_4] &= 1 + \rho(1 + \rho + \rho^2 N) = 1 + \rho + \rho^2 + \rho^3 N \\ E[X_n] &= 1 + \rho + \dots + \rho^{n-2} + \rho^{n-1} N. \end{aligned}$$

Hence,

$$E[X_n] = \frac{1 - \rho^{n-1}}{1 - \rho} + \rho^{n-1} N, n \geq 1.$$

Diluting

By analyzing $E[X_{n+1}|X_n]$, we found that $E[X_n] = N \left(\frac{N-1}{N}\right)^{n-1}$, $n \geq 1$.

Here is another argument for that result.

Consider one particular red ball, say ball k . At each step, it remains red w.p. $(N-1)/N$, when another ball is picked. Thus, the probability that it is still red at step n is $[(N-1)/N]^{n-1}$. Let

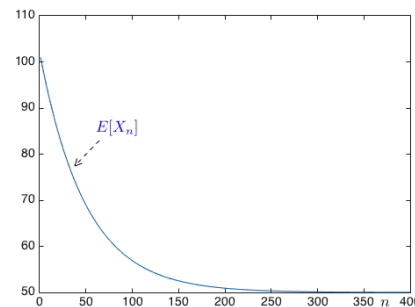
$$Y_n(k) = 1 \{\text{ball } k \text{ is red at step } n\}.$$

Then, $X_n = Y_n(1) + \dots + Y_n(N)$. Hence,

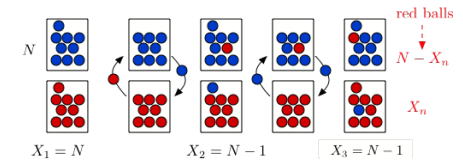
$$\begin{aligned} E[X_n] &= E[Y_n(1) + \dots + Y_n(N)] = NE[Y_n(1)] \\ &= N \Pr[Y_n(1) = 1] = N[(N-1)/N]^{n-1}. \end{aligned}$$

Application: Mixing

Here is the plot.



Application: Mixing



At each step, pick a ball from each well-mixed urn. We transfer them to the other urn. Let X_n be the number of red balls in the bottom urn at step n . What is $E[X_n]$?

Given $X_n = m$, $X_{n+1} = m + 1$ w.p. p and $X_{n+1} = m - 1$ w.p. q where $p = (1 - m/N)^2$ (B goes up, R down) and $q = (m/N)^2$ (R goes up, B down).

Thus, $E[X_{n+1}|X_n] = X_n + p - q = X_n + 1 - 2X_n/N = 1 + \rho X_n$, $\rho := (1 - 2/N)$.

Application: Going Viral

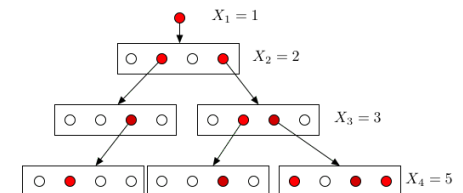
Consider a social network (e.g., Twitter).

You start a rumor (e.g., Walrand is really weird).

You have d friends. Each of your friend retweets w.p. p .

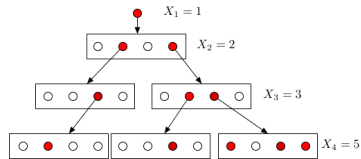
Each of your friends has d friends, etc.

Does the rumor spread? Does it die out (mercifully)?



In this example, $d = 4$.

Application: Going Viral



Fact: Let $X = \sum_{n=1}^{\infty} X_n$. Then, $E[X] < \infty$ iff $pd < 1$.

Proof:

Given $X_n = k$, $X_{n+1} = B(kd, p)$. Hence, $E[X_{n+1}|X_n = k] = kpd$.

Thus, $E[X_{n+1}|X_n] = pdX_n$. Consequently, $E[X_n] = (pd)^{n-1}$, $n \geq 1$.

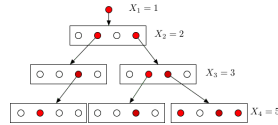
If $pd < 1$, then $E[X_1 + \dots + X_n] \leq (1 - pd)^{-1} \Rightarrow E[X] \leq (1 - pd)^{-1}$.

If $pd \geq 1$, then for all C one can find n s.t.

$$E[X] \geq E[X_1 + \dots + X_n] \geq C.$$

In fact, one can show that $pd \geq 1 \Rightarrow Pr[X = \infty] > 0$. □

Application: Going Viral



An easy extension: Assume that everyone has an independent number D_i of friends with $E[D_i] = d$. Then, the same fact holds.

To see this, note that given $X_n = k$, and given the numbers of friends $D_1 = d_1, \dots, D_k = d_k$ of these X_n people, one has $X_{n+1} = B(d_1 + \dots + d_k, p)$. Hence,

$$E[X_{n+1}|X_n = k, D_1 = d_1, \dots, D_k = d_k] = p(d_1 + \dots + d_k).$$

Thus, $E[X_{n+1}|X_n = k, D_1, \dots, D_k] = p(D_1 + \dots + D_k)$.

Consequently, $E[X_{n+1}|X_n = k] = E[p(D_1 + \dots + D_k)] = pdk$.

Finally, $E[X_{n+1}|X_n] = pdX_n$, and $E[X_{n+1}] = pdE[X_n]$.

We conclude as before.

Application: Wald's Identity

Here is an extension of an identity we used in the last slide.

Theorem Wald's Identity

Assume that X_1, X_2, \dots and Z are independent, where

Z takes values in $\{0, 1, 2, \dots\}$

and $E[X_n] = \mu$ for all $n \geq 1$.

Then,

$$E[X_1 + \dots + X_Z] = \mu E[Z].$$

Proof:

$$E[X_1 + \dots + X_Z | Z = k] = \mu k.$$

$$\text{Thus, } E[X_1 + \dots + X_Z | Z] = \mu Z.$$

$$\text{Hence, } E[X_1 + \dots + X_Z] = E[\mu Z] = \mu E[Z].$$

□

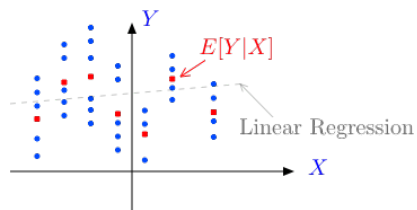
CE = MMSE

Theorem

$E[Y|X]$ is the 'best' guess about Y based on X .

Specifically, it is the function $g(X)$ of X that

$$\text{minimizes } E[(Y - g(X))^2].$$



CE = MMSE

Theorem CE = MMSE

$g(X) := E[Y|X]$ is the function of X that minimizes

$$E[(Y - g(X))^2].$$

Proof:

Let $h(X)$ be any function of X . Then

$$\begin{aligned} E[(Y - h(X))^2] &= E[(Y - g(X) + g(X) - h(X))^2] \\ &= E[(Y - g(X))^2] + E[(g(X) - h(X))^2] \\ &\quad + 2E[(Y - g(X))(g(X) - h(X))]. \end{aligned}$$

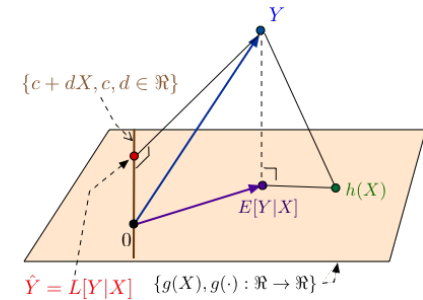
But,

$$E[(Y - g(X))(g(X) - h(X))] = 0 \text{ by the projection property.}$$

$$\text{Thus, } E[(Y - h(X))^2] \geq E[(Y - g(X))^2].$$

□

$E[Y|X]$ and $L[Y|X]$ as projections



$L[Y|X]$ is the projection of Y on $\{a + bX, a, b \in \mathfrak{R}\}$: LLSE

$E[Y|X]$ is the projection of Y on $\{g(X), g(\cdot) : \mathfrak{X} \rightarrow \mathfrak{R}\}$: MMSE.

Summary

Conditional Expectation

- ▶ Definition: $E[Y|X] := \sum_y yPr[Y = y|X = x]$
- ▶ Properties: Linearity,
 $Y - E[Y|X] \perp h(X)$; $E[E[Y|X]] = E[Y]$
- ▶ Some Applications:
 - ▶ Calculating $E[Y|X]$
 - ▶ Diluting
 - ▶ Mixing
 - ▶ Rumors
 - ▶ Wald
- ▶ MMSE: $E[Y|X]$ minimizes $E[(Y - g(X))^2]$ over all $g(\cdot)$